



## Picking Sequences for Resource Allocation

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# A fair division problem...

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- $p$  candies of different kinds and flavors;
- $n$  kids: kid  $A$ , kid  $B$ , kid  $C$ ...



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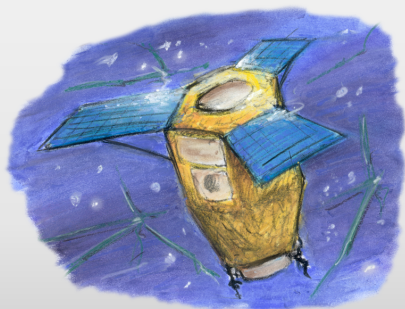
# An ubiquitous problem

- Allocation of courses (or practical works) to students
- Allocation of take-off and landing slots in airports
- Allocation of tasks to workers
- Allocation of jobs to machines
- Allocation satellite resources



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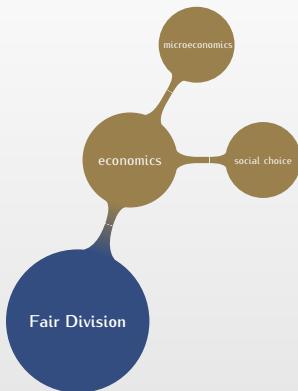
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Fair Division

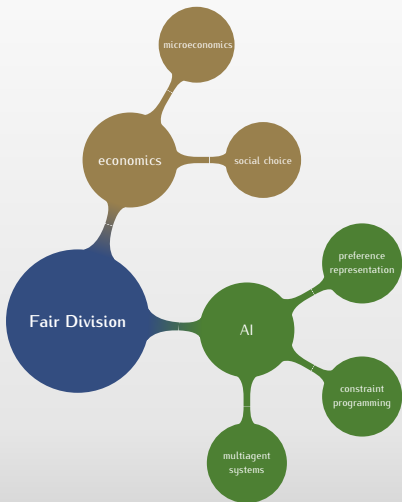


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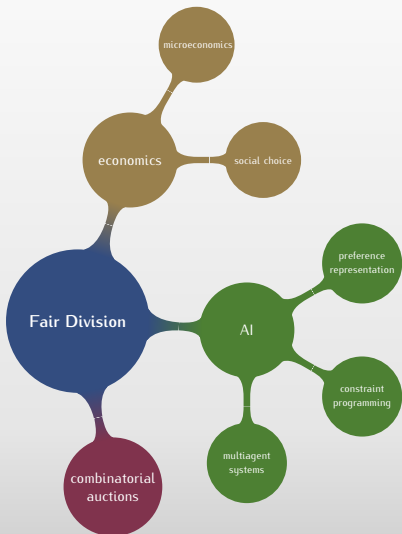


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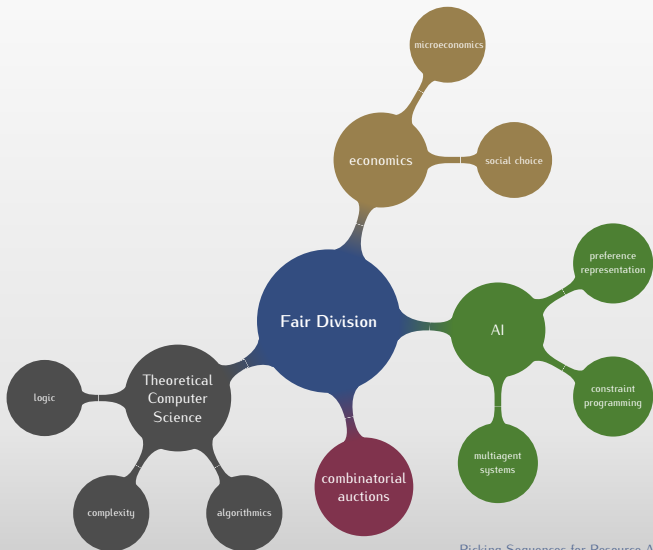


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# Computational social choice

## Computational Social Choice (COMSOC)

COMSOC  $\approx$  Social Choice  $\cap$  Computer Science



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- 1 | Use techniques from economics to solve problems in IT (network sharing, job allocation...)
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## Computational Social Choice (COMSOC)

COMSOC  $\approx$  Social Choice  $\cap$  Computer Science

- 1 | Use techniques from economics to solve problems in IT (network sharing, job allocation...)
- 2 | Use techniques from CS to analyze and solve economical problems (complexity of voting procedures, compact preference representation...)
  - Fair division (indivisible goods or cake-cutting)
  - Voting
  - Coalition formation / hedonic games
  - Judgment aggregation...



# Back to our fair division problem

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- **Answer 1** (the social choice theoretician's): Ask the kids to give their preferences and use a (centralized) collective decision making procedure.
- **Answer 2** (the MAS specialist's): Ask the kids to negotiate.



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## A much simpler procedure...

Ask the kids to pick in turn their most preferred candy among the remaining ones, according to some **predefined sequence**.

### Example

3 kids  $A$ ,  $B$ ,  $C$ , 6 candies, sequence  $ABCCBA \rightarrow A$  chooses first (and takes her preferred candy), then  $B$ , then  $C$ , then  $C$  again...



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We “feel” that  $ABCCBA$  is **fairer** than  $AABBCC$ ...

$\rightarrow$  What is the **fairest** sequence ?

## The model

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What is the best sequence?



## Agents, objects, preferences...

- A set  $\mathcal{O}$  of  $p$  objects  $\{1, \dots, p\}$
- A set  $\mathcal{N}$  of  $n$  agents  $\{A, B, \dots, x\}$
- A central authority (CA) must find a **policy** (a sequence of agents)  
 $\pi : \{1, \dots, p\} \rightarrow \{A, B, \dots, x\}$
- The central authority assumes that each agent  $i$  has a (private) **ranking**  $\succ_i$  over  $\mathcal{O}$  (ex:  $6 \succ 1 \succ 4 \succ 5 \succ 2 \succ 3$ )



# Example

## Example

5 objects, 3 agents,  $\pi = ABCCB\dots$

- A : 1  $\succ$  2  $\succ$  3  $\succ$  4  $\succ$  5
- B : 4  $\succ$  2  $\succ$  5  $\succ$  1  $\succ$  3
- C : 1  $\succ$  3  $\succ$  5  $\succ$  4  $\succ$  2



# Example

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- $A : 1 \succ 2 \succ 3 \succ 4 \succ 5$
- $B : 4 \succ 2 \succ 5 \succ 1 \succ 3$
- $C : 1 \succ 3 \succ 5 \succ 4 \succ 2$

$k$	0
$s(A)_k^\pi$	$\emptyset$
$s(B)_k^\pi$	$\emptyset$
$s(C)_k^\pi$	$\emptyset$
$\mathcal{O}_k^\pi$	$\emptyset$



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$k$	0	1
$s(A)_k^\pi$	$\emptyset$	1
$s(B)_k^\pi$	$\emptyset$	$\emptyset$
$s(C)_k^\pi$	$\emptyset$	$\emptyset$
$\mathcal{O}_k^\pi$	$\emptyset$	1



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- $C: 1 \succ 3 \succ 5 \succ 4 \succ 2$

$k$	0	1	2
$s(A)_k^\pi$	$\emptyset$	1	1
$s(B)_k^\pi$	$\emptyset$	$\emptyset$	4
$s(C)_k^\pi$	$\emptyset$	$\emptyset$	$\emptyset$
$\mathcal{O}_k^\pi$	$\emptyset$	1	14



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- C : 1  $\succ$  3  $\succ$  5  $\succ$  4  $\succ$  2

$k$	0	1	2	3
$s(A)_k^\pi$	$\emptyset$	1	1	1
$s(B)_k^\pi$	$\emptyset$	$\emptyset$	4	4
$s(C)_k^\pi$	$\emptyset$	$\emptyset$	$\emptyset$	3
$\mathcal{O}_k^\pi$	$\emptyset$	1	14	143



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$k$	0	1	2	3	4
$s(A)_k^\pi$	$\emptyset$	1	1	1	1
$s(B)_k^\pi$	$\emptyset$	$\emptyset$	4	4	4
$s(C)_k^\pi$	$\emptyset$	$\emptyset$	$\emptyset$	3	35
$\mathcal{O}_k^\pi$	$\emptyset$	1	14	143	1435



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$k$	0	1	2	3	4	5
$s(A)_k^\pi$	$\emptyset$	1	1	1	1	1
$s(C)_k^\pi$	$\emptyset$	$\emptyset$	4	4	4	42
$s(C)_k^\pi$	$\emptyset$	$\emptyset$	$\emptyset$	3	35	35
$\mathcal{O}_k^\pi$	$\emptyset$	1	14	143	1435	14352



## Scoring functions

We only have rankings over objects...

→ *How to compare two allocations ?*



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Two natural assumptions:

- 1 | **Scoring:** We have a common **scoring function**  $g : \{1, \dots, p\} \mapsto \mathbb{N}$  mapping each rank to a utility.
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Quasi-Indifference	$1 + 5\varepsilon$	$1 + 4\varepsilon$	$1 + 3\varepsilon$	$1 + 2\varepsilon$	$1 + \varepsilon$	1



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5 objects, 3 agents,  $\pi = ABCCB\dots$

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With  $\pi$ , agent  $A$  gets 1, agent  $B$  gets 24, agent  $C$  gets 35



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With  $\pi$ , agent  $A$  gets 1, agent  $B$  gets 24, agent  $C$  gets 35

- **Borda:**  $u_A(\pi) = 5; u_B(\pi) = 5 + 4 = 9; u_C(\pi) = 4 + 3 = 7.$
- **lexicographic:**  $u_A(\pi) = 16; u_B(\pi) = 24; u_C(\pi) = 12.$
- **QI:**  $u_A(\pi) = 1 + 4\varepsilon; u_B(\pi) = 2 + 7\varepsilon; u_C(\pi) = 2 + 5\varepsilon.$



# Social welfare

We use a **collective utility function** to aggregate the individual utilities.

Two well-known functions:

- **utilitarian:**  $F(u_A, \dots, u_x) = \sum_{i \in \mathcal{N}} u_i$ ;
- **egalitarian:**  $F(u_A, \dots, u_x) = \min_{i \in \mathcal{N}} u_i$ .



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The procedure is elicitation-free...

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The CA has a **probabilistic model** of the preferences:

- **Full independence** : each profile  $R = \langle \succ_A, \dots, \succ_x \rangle$  is equally probable
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Expected individual and collective utilities:

$$\overline{u(i, \pi)} = \sum_{R \in \text{Prof}(\mathcal{N}, \mathcal{O})} Pr(R) \times u_i(\pi, R).$$

$$\overline{sw_F(\pi)} = F(\overline{u(1, \pi)}, \dots, \overline{u(n, \pi)}).$$



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### Example

5 objects, 3 agents,  $\pi = ABCCB$ ,  $g = g_{Borda}$ , full independence.  
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3's preferences: ?  $\succ$  ?  $\succ$  ?  $\succ$  ?  $\succ$  ?

$$\overline{u(3, \pi)} =$$



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$$\overline{u(3, \pi)} = \frac{1}{\binom{5}{2}} \times (3 + 2)$$



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3's preferences:  $? \succ ? \succ ? \succ ? \succ ?$

$$\overline{u(3, \pi)} = 0.5 + \frac{1}{\binom{5}{2}} \times (4 + 2)$$



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$$\overline{u(3, \pi)} = 0.5 + 0.6 + \frac{1}{\binom{5}{2}} \times (5 + 2)$$



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*What is agent 3's expected utility with this sequence ?*

3's preferences:  $? \succ ? \succ ? \succ ? \succ ?$

$$\overline{u(3, \pi)} = 0.5 + 0.6 + 0.6 + \frac{2}{\binom{5}{2}} \times (4 + 3)$$



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*What is agent 3's expected utility with this sequence?*

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$$\overline{u(3, \pi)} = 0.5 + 0.6 + 0.6 + 1.4 + \frac{2}{\binom{5}{2}} \times (5 + 3)$$



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What is agent 3's expected utility with this sequence ?

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5 objects, 3 agents,  $\pi = ABCCB$ ,  $g = g_{Borda}$ , full independence.

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$$\overline{u(3, \pi)} = 0.5 + 0.6 + 0.6 + 1.4 + 1.6 + 2.7 = \mathbf{7.5}$$



# Summary

- **Instance:**

- a number of agents  $n$
- a number of objects  $p$
- a scoring function  $g$
- a correlation profile  $Corr \in \{FC, FI\}$
- a collective utility function  $F$

- **Question:**

- *What is the policy  $\pi$  maximizing  $\overline{sw_F(\pi)}$ , under correlation profile  $Corr$  ?*



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Sequential allocation is **NP**-complete.

(Reduction from [PARTITION])



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All policies have the same expected value!

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Sequential allocation is **NP**-complete.

(Reduction from [PARTITION])

What about...

- ...lexicographic scoring ?
- ...quasi-indifference scoring ?
- ...Borda scoring ?



# Lexicographic scoring

$\gamma_i$	6	$\gamma$	1	$\gamma$	4	$\gamma$	5	$\gamma$	2	$\gamma$	3
lexicographic	32	>>	16	>>	8	>>	4	>>	2	>>	1

## Egalitarian CUF (min)

**Optimal policies:**  $\sigma(A)\sigma(B)\dots\sigma(x)\sigma(x)^{p-n}$  (where  $\sigma$  is a permutation of  $\{A, B, \dots, x\}$ )



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**Example:**  $\pi = ABCCCC$

- $\overline{u(1, \pi)} = 32$
- $\overline{u(2, \pi)} = 16$
- $\overline{u(3, \pi)} = 8 + 4 + 2 + 1 = 15$



# Borda scoring

$\gamma_i$	6	1	4	5	2	3
Borda	6	5	4	3	2	1



# Borda scoring

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This is **polynomial** in  $p$  (dynamic programming algorithm).



## QI scoring

$\succ_i$	6	1	4	5	2	3
Quasi-Indifference	$1 + 5\varepsilon$	$1 + 4\varepsilon$	$1 + 3\varepsilon$	$1 + 2\varepsilon$	$1 + \varepsilon$	1

### Egalitarian CUF (min)

Comes down to solving the Borda case!



# QI scoring

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## Egalitarian CUF (min)

Comes down to solving the Borda case!

### Intuition:

- let  $m = \lfloor \frac{p}{n} \rfloor$  and  $q = p - nm$

- Optimal policies:  $\pi = \underbrace{AABB}_{n-q \text{ agents}} \overbrace{CCDDDD}^{q \text{ agents}}$  and  $\pi' = \underbrace{ABBA}_{n-q \text{ agents}} \overbrace{CCDDDD}^{q \text{ agents}}$

- The  $q$  last agents are OK  $\rightarrow u \geq m + 1$
- The  $n - q$  first agents:  $u = m + x \cdot \varepsilon$  ( $x \rightarrow$  Borda)



# A complex problem...

## 2. Full independence



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### Conjecture (2011)

Computing the expected utility of a sequence is **NP**-complete.  
Computing the **optimal** sequence probably harder.



# Results

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**polynomial** [Kalinowski et al., 2013].



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# Results

Computing the expected utility of a sequence is **NP-complete polynomial** [Kalinowski et al., 2013].

Computing the **optimal** sequence probably harder.

- the **alternating policy** (*ABABABAB...*) is optimal for Borda, utilitarian social welfare
- complexity unknown for other social welfare and scoring functions (**NP-hardness** conjectured)



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## Some examples

**Assumptions:** Full independence, egalitarian CUF, Borda scoring function.

$p$	$n = 2$	$n = 3$
4		
5		
6		
8		
10		



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$p$	$n = 2$	$n = 3$
4	ABBA	ABCC
5	AABBB	ABCCB
6	ABABBA	ABCCBA
8	ABBABAAB	AACCBBCB
10	ABBAABABBA	ABCABBCACC



## Some examples

**Assumptions:** Full independence, egalitarian CUF, Borda scoring function.

$p$	$n = 2$	$n = 3$
4	ABBA	ABCC
5	AABBB	ABCCB
6	ABABBA	ABCCBA
8	ABBABAAB	AACCBBCB
10	ABBAABABBA	ABCABBCACC

Other examples on  
<http://recherche.noiraudes.net/en/sequences.php>

## Strategical issues (manipulation)

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Is the protocol strategy-proof?



# Manipulation?

- A set  $\mathcal{O}$  of  $p$  objects  $\{1, \dots, p\}$
- A set  $\mathcal{N}$  of  $n$  agents  $\{A, B, \dots, x\}$
- A central authority (CA) has chosen a **policy**  $\pi$  and will execute it
- The agents have their own private preferences  $\rightarrow$  **picking strategy**.



# Manipulation?

## Example

2 agents, 4 objects:

- A:  $1 \succ 2 \succ 3 \succ 4$
- B:  $2 \succ 3 \succ 4 \succ 1$

Sequence  $\pi = ABBA \rightarrow \{14|23\}$ .



# Manipulation?

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Sequence  $\pi = ABBA \rightarrow \{14|23\}$ .

*What if A knows B's preferences and acts maliciously?*



# Manipulation?

## Example

2 agents, 4 objects:

- A:  $1 \succ 2 \succ 3 \succ 4$
- B:  $2 \succ 3 \succ 4 \succ 1$

Sequence  $\pi = ABBA \rightarrow \{14|23\}$ .

*What if A knows B's preferences and acts maliciously?*

She can manipulate by picking 2 instead of 1 at first step  $\rightarrow \{12|34\}$ .



## More formally

- A set  $\mathcal{O}$  of  $p$  objects  $\{1, \dots, p\}$
- A set  $\mathcal{N}$  of  $n$  agents  $\{A, B, \dots, x\}$
- A **policy**  $\pi$
- The agents have their own private preferences (which may or may not be additive) and use them for their **picking strategy**.



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### The cheating agent ( $A$ ) knows:

- the sequence
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### She wants:

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### Her only possible cheating actions:

- choose at given steps **not** to pick her preferred objects.



## First result

A: *“Can I get  $S$  for sure?”*





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### Getting a subset for sure

---

We can answer to that constructively in polynomial time!



# First result

A: *“Can I get  $\mathcal{S}$  for sure?”*

## Getting a subset for sure

We can answer to that constructively in polynomial time!

### Idea:

- two agents: pick the objects in  $\mathcal{S}$  in reverse order of  $\succ_B$
- more agents:
  - transform agents 2 to  $m - 1$  into a single (fake) agent
  - apply the algorithm for 2 agents



## General manipulation problem

A: *“What is the best subset I can get?”*



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**Idea:** Greedily build the optimal achievable subset:

- Find the best object  $i$  such that  $\{i\}$  is achievable;
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If the manipulator has additive preferences, the optimal manipulation can be computed in polynomial time.



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## Manipulation with additive preferences, two agents

If the manipulator has additive preferences, the optimal manipulation can be computed in polynomial time.

Only works **for two agents!**



# General manipulation problem

## Manipulation with additive preferences

If the manipulator has additive preferences, the optimal manipulation problem is **NP**-complete.

(reduction from [3-SAT])



# Coalitional Manipulation

## Example

3 agents, 6 objects:

- A: 1  $\succ$  2  $\succ$  5  $\succ$  4  $\succ$  3  $\succ$  6
- B: 1  $\succ$  3  $\succ$  5  $\succ$  2  $\succ$  4  $\succ$  6
- C: 2  $\succ$  3  $\succ$  4  $\succ$  1  $\succ$  5  $\succ$  6

Sequence  $\pi = ABCABC \rightarrow \{15|34|26\}$ .



# Coalitional Manipulation

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Sequence  $\pi = ABCABC \rightarrow \{15|34|26\}$ .

- If A and B manipulate alone, they cannot do better
- If they cooperate, they can get  $\{12|35|46\}$ , which is strongly better.



## Coalitional Manipulation: Results

Three kinds of manipulation considered here:

- No post-allocation trade allowed between the manipulators
- Post-allocation exchange of goods allowed between the manipulators
- Post-allocation exchange of goods + side-payments allowed



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## Results:

- No post-allocation trade allowed between the manipulators → NP-complete [PARTITION]
- Post-allocation exchange of goods allowed between the manipulators → NP-complete [PARTITION]
- Post-allocation exchange of goods + side-payments allowed → polynomial (comes down to manipulation by a single agent)



# Everyone manipulates...

One manipulator





## Everyone manipulates...

One manipulator  $\rightarrow$  several manipulators (coalitional manipulation)



---

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One manipulator → several manipulators (coalitional manipulation)  
→ everyone (rational, self-interested) manipulates?



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**Game Theory** (Subgame Perfect Nash Equilibrium)



# Everyone manipulates...

One manipulator  $\rightarrow$  several manipulators (coalitional manipulation)  
 $\rightarrow$  everyone (rational, self-interested) manipulates?

## Game Theory (Subgame Perfect Nash Equilibrium)

- Two agents and additive utilities, precise characterization of the result of every SPNE  $((rev(\succ_2), rev(\succ_1), rev(\pi)))$   
 [Kalinowski et al., 2013, Kohler and Chandrasekaran, 1971].
- Unbounded number of agents: **PSPACE**-hard [Kalinowski et al., 2013].



**Kalinowski, T., Narodytska, N., Walsh, T., and Xia, L. (2013).**

Strategic behavior when allocating indivisible goods sequentially.  
*In Proceedings of AAAI'13.*



**Kohler, D. A. and Chandrasekaran, R. (1971).**

A class of sequential games.  
*Operations Research, 19(2):270–277.*

## Conclusion

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A take-away message?



# Conclusion

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- A simple and intuitive sequential allocation procedure (actually already known in sparse literature)
- Finding the best policy?
  - Full Correlation case well understood
  - Full Independence: partial results
- Strategic issues: individual and coalitional manipulation; game-theoretic approach



# Sequenceability and Pareto-optimality

Another interesting property [Brams and King, 2005]:  
Sequenceability exactly characterizes allocations that are ordinally necessary Pareto-optimal.

(an allocation can be generated by a sequence if and only if it is ordinally necessary Pareto-optimal)



**Brams, S. and King, D. (2005).**

Efficient fair division: Help the worst off or avoid envy ?  
*Rationality and Society*, 17:387–421.